Total No. of Questions : 12 [Total No. of Printed Pages :2]

B.E. Production. Examination - 2013 APPLIED SCIENCE -Production Management.

[Time : 3 Hours] Instructions :

- (1) Answer any 3 questions from each section.
- (2) Answers to the two sections should be written in separate answer-books.

(3) Figures to the right indicate full marks.

(4) Use of logarithmic tables slide rule, Mollier charts,

Electronic packet calculator and steam tables is allowed.

- (5) Neat diagrams must be drawn whenever necessary.
- (6) Assume suitable data, if necessary.

# <u>Section- I</u> <u>Unit –I</u>

Q1. (a) Differentiate between production and production management. Explain in<br/>brief objectives of Production management.(08)(b) Explain Product life cycle in brief.(08)

OR

Q2. (a) Explain production interface with other functional area of the business such as purchasing, personal, finance, material, maintenance & ppc etc. (08)
(b) Explain standardization, simplification and specialization in relation of product design & development . (08)

#### Unit II

Q3.	(a)	Explain	different	princip	les and	material	handling.	(0	)8)
·	~ /	1		1 1			0		

(b) Explain principles and plant layout.

#### OR

Q4. (a) What are the factors considered while selecting location for an foundry plant? (08)

(b) What are the different types of plants layout? Explain any one with its advantages & disadvantages with its application. (08)

[Max. Marks : 100]

(08)

#### Unit III

- Q5 (a) Explain in detail what do you understand Manpower Inventory. (09)
- (b) What is productivity Improvement program (PIP)? Explain (09)

#### OR

Q6. (a) Explain different productivity Ratios.

casting.

What are the different factors affect as productivity.(09)(b) Explain different factors considered for resources (man power) supply fore

(09)

#### Section-II

#### Unit IV

Q7. (a) Explain in brief evolution of world class manufacturing (WCM).	(09)
(b) Explain in brief Maskal's model of WCM.	(09)

#### OR

Q8. (a) What is manufacturing excellence through value add manufacturing? (09)(b) What are the business challenges in information age? (09)

#### Unit v

Q9 a)What is Industrial maintenance explain primary and secondary functions of maintenance? (08)

- (b) Explain how performance of maintenance function is evaluated? (08) OR
- Q10. (a) What are the operating practices used to reduce maintenance work? (08)

(b) Explain the concept of total productive maintenance (TPM)in brief. (08)

#### Unit-VI

Q11. (a) Explain "Green manufacturing in brief.	(08)
(b) What are the responsibilities of Industrialists Environment and	
Ecology.	(08)

#### OR

Q12. (a) Explain the types of energy audit? Explain each type in brief.(08)(b) Explain "Lean Manufacturing" in brief.(08)

# UNIVERSITY OF PUNE [4364]-84 B.E. (Production) Examination - 2013 Advance Material Processing (2003 Course)

[Total No. of Questions: 12] [Time: 3 Hours] [Total No. of Printed Pages: 3] [Max. Marks: 100]

# Instructions:

- (1) Answer three questions from each section-I and three questions from section-II.
- (2) Black figures to the right indicate full marks.

# SECTION-I

Q. 1. A) Explain with neat sketch regarding to hard part machining.	(8)
ii) Typical were types in CBN finish hard turning	
B) Explain cutting speed ranges for seven typical machining	(8)
operation and materials of different machining rating.	(-)
OR	
Q.2. a) Describe with neat sketch following special machining processer	(16)
i. Oscillating turning	
ii. Vibration Assisted machining	
Q.3 Explain with neat sketch ultrasonic impact grinding.	
a) Process and also describe the various characteristics of USM	(10)
process.	
b) Describe advances in thermal energy method.	(6)
OR	
Q.4 Describe	(16)
i. Chemical milling	
ii. Photochemical milling	
Q. 5 a) Explain with the help of neat sketch advance in following forming	(18)
processes.	
i. Ring rolling	
ii. Forging of stainless steel	
OR	
Q. 6 a) Write a short note on	(18)
i. Auto for cast processes.	
ii. Impact Extrusion	

# **SECTION-II**

Q. 7 a) Explain with the help of neat sketch following advanced casting	(16)
Processes.	
1. Injection casting	
ii. Continuous casting	
OR	
Q. 8 Write a short note on	(16)
i. Asarco process	
ii. Direct chill process	
Q. 9 a) Explain with neat sketch ceramic shell process.	(8)
b) Describe master mould casting	(8)
OR	
Q. 10 Describe following process equipment	(16)
i. Forming	
ii. Moulding	
Q. 11. Explain with neat sketch	
a) Different surface cleaning methods	(12)
b) Explain briefly Mano surface machining method.	(6)
OR	
Q. 12 Write a short note on	(18)
<ul><li>i. Ligo technique for fabrication</li><li>ii. MEMS fabrication</li></ul>	

iii. Polymer

#### **University of Pune**

#### **Examination May 2013**

#### B. E. (Production) (2003 Course) 4364-74

#### Sub: OPERATIONS RESEARCH

#### Instructions:

- 1. Answers to two sections should be written in separate answer sheets
- 2. Solve Q1 or 2, Q3 or 4, Q5 or 6, Q7 or 8, Q9 or 10, Q11 or 12

#### SECTION -I

- 1. (a) What is significance of duality theory in LPP? "Dual of Dual is primal" explain in brief. [6]
  - (b) Use the two phase method to

minimize Z=x<sub>1</sub>+x<sub>2</sub>

S. t.  $2x_1+x_2 \ge 4$ 

 $x_1 + 7x_2 \ge 7$ 

x<sub>1</sub>,x<sub>2</sub>≥0

#### OR

[10]

2. (a) Express linear programming problem in its general, canonical & standard form. [6]
(b) Find the optimal solution by simplex method [10]

 $\begin{array}{l} \text{Min. } z = x_2 + 3x_3 + 2x_5 \\ \text{s.t. } 3x_2 - x_3 + 2x_5 \geq 7 \\ -2x_2 + 4x_3 \geq 12 \\ -4x_2 + 3x_3 + 8x_5 \geq 10 \\ x_2, x_3, x_5 \geq 0 \end{array}$ 

3. (a) Explain the similarities and differences between transportation and transshipment problem [6]

(b) Find the optimum solution to the following transporation problem in which the cells contain the transportation cost in Rs. [12]

	W1	W2	W3	W4	W5	Available
F1	7	6	4	5	9	40
F2	8	5	6	7	8	30
F3	6	8	9	6	5	20
F4	5	7	7	8	6	10

Required	30	30	15	20	5	100(Total)
----------	----	----	----	----	---	------------

OR

- 4. (a) Discuss the assignment model Indicate the method of solving the traveling salesman problem. [8](b) State the comon and distinguishing features of assignment model and write its applications. [10]
- 5. (a) Explain the concept of Gomory's cutting plane method. [8]
  - (b) State the Bellman's principle of optimiality and explain how it is used for solving dynamic programming problem. [8]

OR

6 (a) Write note on integer programming and non-linear programing. [8]

(b) Solve the following problem by branch and bound method: [8] Max.  $z=x_1+x_2$ S. t.  $3x_1+2x_2\leq 20$  $6x_1+5x_2\leq 25$  $X_1+3x_2\leq 10$ 

 $X_1$ ,  $x_2$  are non negative integers.

#### SECTION -II

7. (a) Write a note on goal programming. [8]

(b) A system contains 10000 resistors. When any register fails it is replaced. The cost of replacing each resistor is Rs. 1. If all registers are replaced at a same time the cost per register is reduced to 35 paise. The percent surviving at the end of the month are:

End of	0	1	2	3	4	5	6
month							
Probability of failure	0	0.04	0.06	0.25	0.30	0.15	0.20
during the							
month							

What is optimum replacement plan? [8]

OR

8. (a) Explain the concept of geometric programming. [8]

(b) Manufacturer produces 2 products A and B using two limited resources labour and raw material. A unit of product A requires 2 Hrs. of labor time and 3 units of raw material while a unit of product B

requires 4 Hrs. of labour time and 4 units of raw material. Everyday 28 Hrs. of labor time and 32 units of raw material are available. The goal before him in accordance with priorities atre as follows:

1) The profit per day should be atleast Rs. 44 assuming that the profit per unit of Product A and B is Rs. 8 and Rs. 6 respectively.

2) No. of units of product A produces should be twice that of B

3) The labor time should be fully utilised.

Formulate G. P. model for the problem and solve using G. P. [10]

#### 9. (a) Explain in brief the characteristics of queing models. [8]

(b) A branch of Punjab National bank has only one typist. Since the typist work varies in length, the typing rate is randomly distributed approximating the poissons distribution with a mean service rate of 8 letters per hr. The letters arrive at rate of 5 per Hr. during 8 Hr. work day. If the typewriter is valued at Rs. 1.5 per Hr. Determine

#### 1. Equipment utilisation

2. The percent time the arrival letter to wait

- 3. Average system time
- 4. Average cost due to waiting on the part of typewriter. [10]

OR

#### 10. (a) Explain the Kendal notation for representing the queing models. [6]

b) Find the saddle point and hence solve the following game: [10]

	B1	B2	B3	B4
A1	1	7	3	4
A2	5	6	4	5
A3	7	2	0	3

11. (a) Explain the following terms: a) earliest time b) latest time c) slack d) event [8]

(b) A project schedule has following characteristics: [8]

Activity	Time	Activity	Time
1-2	2	4-8	8

1-4	2	5-6	4
1-7	1	6-9	3
2-3	4	7-8	3
3-6	1	8-9	5
4-5	5		

a)Construct the PERT network, find critical path and time duration of project.

b) Total float for each activity.

OR

#### 12. (a) Explain the following: [8]

- i) Difference between PERT and CPM
- ii) Resource smoothing
- iii) Dummy in network analysis
- iv) Difference between activity and event.

(b) Consider the following project: [8]

Activity	Predecessor	Optimistic	Most likely	Pessimistic
А	-	3	6	9
В	-	2	5	8
С	А	2	4	6
D	В	2	3	10
E	В	1	3	11
F	C,D	4	6	8
G	E	1	5	15

- a) Draw network diagram for project.
- b) Dtermine the critical path.
- c) Calculate the variance and standard deviation.
- d) What is probability that project will be completed by 18 weeks.

Z	0	0.5	1	1.5	2.0
Probability	0.5	0.692	0.841	0.933	0.977

# UNIVERSITY OF PUNE (4364)-72 B.E. (Production Sandwitch & Production) Examination – 2013 MACHINE TOOL DESIGN (2003 Pattern)

[Time: 3 Hours][Max. Marks: 100]Total No. of Questions : 12[Total No. of Printed Pages :2]

#### **Instructions:**

- (1) Answers any five.
- (2) Figures to the right indicate full marks.
- (3) Neat diagrams must be drawn whenever necessary.

# **SECTION I**

Q1 a) Discuss the basic design procedure of machine tool structures.	[10]
b) Explain why box type structure is adapted for construction of machine tools.	[5]
c) Draw and Explain commonly used machine tool bed wall arrangements ar mention their applications.	nd [5]
Q2. a) Explain with examples "working" and "auxiliary"	[7]
b) State the advantages and limitation of a hydraulic drive.	[6]
c) Explain with a diagram, the features of positive infinity variable drive (Pl	[V) [7]
Q3. a) Discuss the recent trend in machine tools in the industry.	[7]
b) Discuss the design requirements for SPM machine tool in an industry.	[7]
c) Design layout of machine tool using matrices.	[6]

# **SECTION II**

Q4. a) Explain with sketches, the following shapes of guide ways. i) Flat ii) "V' Type iii) Dovetail type.	
State their advantages & applications.	[10]
b) State the functions and requirements of guide ways.	[5]
c) Explain advantages of ball screws over.	[5]
Q5. a) Compare the performance of hydrostatic and hydrodynamic bearings used for spindle supporting machine tool.	[5]
b) Discuss the function of spindle unit and it's design requirements	[5]
c) State the advantages of antifriction bearings used for supporting machine to spindles. Also mention the specific advantage of angular contact bearing.	tool ball [5]
d) Sketch & explain hydrostatic journal.	[5]
<ul><li>Q6. Explain the different sources of vibrations in.</li><li>A) Machine tools. Also explain the effects of these vibrations. [</li></ul>	10]
B) Enumerate the functions and requirements of a machine tool control system	ι.

[10]

# UNIVERSITY OF PUNE [4364]-73 B.E.(Semester - I) Examination -2013 B.E (Production) Manufacturing automation and control (2003 Course)

[Time : 3 Hours][Max. Marks:100]Total No. of Questions : 12[Total No. of Printed Pages :3]

Instructions :

- (1) Answer any three questions from each section.
- (2) Answers to the **two sections** should be written in **separate answer-books**.
- (3) Black figures to the right indicate full marks.
- (4) Neat diagrams must be drawn wherever necessary.
- (5) Use of logarithmic tables, slide rule, Mollier charts, electronic pocket calculator and steam tables is allowed.
- (6) Assume suitable data, if necessary.

# **SECTION 1**

- Q.1 a) Derive the expression for flow in case of swash plate type axial [8] piston pump.
  - b) A pump with a delivery of 25 lpm is fed into a pipe with total volume [4] of 20 liters. if the end of pipe is suddenly blocked, calculate the rise in pressure after 4 seconds if bulk modulus is 1800mpa.
  - c) Explain with neat sketch the hydraulic circuit showing the application [4] of counterbalance vale

# OR

Q.2 a ) Explain various criteria for selection of a hydraulic pump. [8]
b) A mass of 3000 kg is to be accelerated from rest to a velocity of 2 m/s [8]
over a distance of 65mm. Calculate the bore diameter of cylinder if coefficient of friction between load and guide is 0.15.

Q.3 a) A hydraulic system requires 275 I/ min at 45 bar for 20 seconds and [8] 25 I/min at 365 bar pressure for 30 seconds. Compare the efficiency of the system when operated with and without pressure intensifier.

b) Explain hydraulic servo mechanism.

#### OR

[8]

Q.4 a) Explain with neat sketch the working principle of regenerative circuit. [8]

b) A hydraulic system having total cycle time of 42 seconds required 18 [8]
I/min flow for 10 seconds. Determine the size of gas accumulator assuming isothermal expansion and compression of gas. Assume discharge pressure 150 MPa.

- Q.5 a) Explain the use of turbulence amplifier for logic circuit. [6]
  - b) Explain with neat sketch the working of a time delay valve. [6]
  - c) Explain the advantages of pneumatic system over hydraulic system [6]

#### OR

Q.6 a) Draw a pneumatic circuit to actuate the cylinder if sensors C and D [10] are in the same state [ON or OFF] as that of sensor B and sensor A is in opposite state.

b) Explain with suitable example the use of twin pressure valve as [8] AND gate.

#### **SECTION 2**

Q.7 a) How many status flag does 8085 have? Discuss the role of each flag. [8]

b) Explain the digital to analog converter as an input device. [8]

#### OR

Q.8 a) Explain with suitable example the use of accumulating time in PLC [8]

b) Draw ladder diagram that can be used to start a motor and then after a [8]

delay of 120 second start a pump. When the motor is switched off there should be a delay of 15 second before the pump is switched off.

Q.9 a) Explain the operation of PLC with suitable sketch.	[8]
b) Explain with suitable example the use of counters in PLC.	[8]
OR	
Q.10 a) How would a derivative controller with $k_D = 5_s$ responds to an error that varies as 1.8 sin [0.08t]?	· [6]
b) Explain linear feedback control system.	[10]
Q.11 a) Derive an expression for the limiting velocity of escapement of the cylindrical workpiece through a slot.	[6]
b) Explain with neat sketch various rotary transfer devices.	[6]
c) Explain with suitable example the gravity fed magazine, weight operated magazine, and friction fed magazine.	[6]
OR	
Q.12 ) Write short notes on :	[18]
a) Turn table for orientation of workpiece	
b) Non-vibratory feeders	
Design for a design of the second sec	

c) Design for automated assembly

# **UNIVERSITY OF PUNE**

# [4364-75]

# **B.E.(Production Engineering & Industrial Engineering)**

# **Examination 2013**

# **Reliability Engineering**

(2003 pattern)

**Time-Three hours** 

# [Total No. of Question=11]

Maximum Marks-100

[Total no. of printed pages= 6]

# **Instructions:**

(1)Answer any 3 questions from each section.

(2)Answer to the TWO sections should be written in separate answer books

(3)Neat diagrams must be drawn whenever necessary.

(4)Figures to the right indicate full marks.

(5)Use of non-programmable electronic pocket calculator is allowed.

(6)Assume suitable data whenever necessary.

# **SECTION-I**

Q.1 (a)A series of test conducted under certain stipulated conditions on 800 electronic components, the total duration of tests is 15 hrs. The number of components that fail during each hourly interval id noted. The results obtained are tabulated as shown in table.

(12)

Time (t)	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
No. of	0	120	85	71	62	53	45	41	37	35	29	50	45	63	35	29
Failur																
es																

Based on the failure data or survival test results shown in table.Define

& Calculate failure density(fd):Failure rate(Z)and Reliability (R).

(b)Explain with neat sketch different failure modes of 'Bath tub' curve. (4)

# OR

Q.2 (a)In order to test the strength of a new glue,ten similar structures constructed using the glue were subjected to a continuous vibratory load, and the duration of survival of each structure was noted,the values obtained the following.

Specimen Numbers	1	2	3	4	5	6	7	8	9	10
Hours of survival	60	62	58	50	61	55	59	62	54	55

Calculate the mean time to failures (MTTF) from this data.

(b)In a test involving continuous satisfactory performance of 110

electronic instruments under excessive vibration conditions, the following

failure frequencies were observed, the total test period being 8 hrs. (6)

Time interval	0-1	1-2	2-3	3-4	4-5	5-6	6-7	7-8
Number of failures	3	16	22	42	11	9	4	3

Calculate the mean time to failures (MTTF)From this data.

(c)Define reliability & discuss in it details.

(4)

Q.3 (a)Explain the concept of "Techno-Physico Constraints' with a conceptual system.

(b)Construct a fault tree from.Fig .1 such that the top event is a system failure and component failures are basic events.If  $Pr \{A\}=Pr\{B\}=0.9$ ,

 $Pr{C}=Pr{D}=0.8$  and  $Pr{E}=Pr{F}=0.75$ , compute the probability of the top event. (10)





Q.4 (a)Construct a reliability block diagram for given fault tree. Fig.2 (8)



(b)Differentiate between :Design FMEA and Process FMEA. Explain methodology of system analysis.

(8)

Q.5 (a)Explain with neat sketch 1)Series Configuration 2)General Series-Parallel configuration.

(b)Find the system reliability of the configuration fig.3 (8)

(10)



OR

Q.6 (a)Find the reliability of the configurations shown below in fig 4. (8)



Fig. No. 4

(b)Explain with neat sketch.1)Parallel Configuration 2)General Parallel-Series configuration. (10)

# **SECTION-II**

Q.7 (a)Define Tero-Technology and state the importance of the same in evolving the "LCC" of an asset. (8)

(b)A company is planning to acquire a truck. Two makes of truck are available

in the market. The cost of garaging and the driver's wages are same for both.

(8)

Parameters	Truck A	Truck B
Capital cost	Rs.5 Lakhs	Rs.3 Lakhs
Annual Road Tax & Insurance	Rs.8000	Rs.7000
Operating cost (a)Fuel consumption (b)oil consumption (c)Fuel cost (d)oil cost	20Km/Lit 2 lit/1000km Rs.3/lit 25/lit.	20Km/Lit 2 lit/1000km Rs.3/lit 25/lit.
Maintenance Cost (a)Service interval (b)cost of service (c)random breakdown (d)cost of breakdown	Every 7000 km. Rs.3,000 Every 30,000km Rs 9,000	Every 4000 km. Rs.5,000 Every 10,000km Rs 6,000
Expected life	10 yrs.	10 yrs.

Calculate annual maintenance cost for a period of 30,000 km & find out which truck is advantageous? (8)

# OR

Q.8 (a)Explain mean ,median and mode ranking method.

(8)

(b)The following data refer to 'Mean time to failure 'of a equipment used

in electric power house installation.

No.of failure	1	2	3	4	5	6	7	8	9
MTTF/M TBF(Hrs)	31.3	45.9	78.3	22.1	2.3	4.8	8.1	11.3	17.3

Plot the reliability against time using the method median statistics .How will values changes with mean statistics? (8)

# Q.9 (a)Explain 1)Inherent availability 2)Achieved availability3)Operational availability. (6)

(b)Derive an expression  $Rp(t) = e^{-\lambda t} + e^{-\lambda 2t} - e^{-(\lambda t + \lambda 2)t}$ . (10)

OR

Q.10 (a)What do you mean by the terms grouped ,ungrouped and censored data. (6)(b)the following data have been collected at the plant. (6)

Mean time before failure=60hrs

Mean time to repair =30 hrs.

Administrative logistic time is 30 % of /mean Down Time.(MDT).

Calculate the operational availability and inherent availability of the plant.

(c)Explain the term availability and inherent availability of the plant. (4)

Q.11 Write a short note on.(Any 3) (18)

(1)Mixed configuration in system reliability

(2)Reliability & Quality

(3)k out of m systems

(4)Types of maintenance system

(5)Risk priority number in FMEA

(6)"Tie-set" & "cut set".

#### 4364-77

# B. E. (Production)- 2003 Course <u>Plant Engineering and Maintenance</u> SECTION I

- **Q: 1** (a) What is the effect of maintenance function on productivity of a firm. [8]
  - (b) Explain with suitable example the effect of social, legal, and political factors on selection of plant location. [8]

#### 

- Q: 2 (a) What factors should be considered for site selection of (i) educational instituions (ii) Hotels and restaurants (iii) Banks (iv) Hospitals [8]
  - (b) How will you estimate the capacity requirement for water and manpower for a plant [8]
- Q: 3 (a) Which are the various charting techniques used in 'flow of materials' analysis of stage of SLP.[8]
  - (b) A manufacturer is interested in creating a cellular manufacturing layout with its current machines. A chart below shows the machines required by each part and the sequence of operations. Organise the machines and parts into two production cells that minimises the number of exceptional parts. [8]

				Parts	S			
		1	2	3	4	5	6	
	А	1	1			1		
	В			1	1			
Machines	С	2	2					
	D		3	2			1	
	Е	3				2		
	F				2		2	

#### <u> 0R</u>

**Q: 4** (a) What is significance of PQ analysis and PQRST concept in systamatic plant layout.

- (b) Explain in short various fire prevention practices. [8]
- **Q: 5**(a) Explain following principles of material handling. [10]
  - i) Space ii) Gravity iii) Simplification iv) Unit load v) System approach
    (b) In a automated material handling system AGVs are used for material handling. A number of deliveries and empty returns are indicated in a from-to chart in Table 1. The corresponding distances are indicated in Table 2. The speed of an AGV is 100 ft/min. Considering a traffic factor of 0.9, determine: [8]
    - i) The total transport work.
    - ii) Average total time per delivery, the handling system efficiency, and the resulting average number of deliveries per hour.
    - iii) Number of vehicles needed to satisfy the indicated deliveries per hour.

	<b>Table 1</b> : F	rom-To chart	showing num	per of moves	per hour between	different stations
--	--------------------	--------------	-------------	--------------	------------------	--------------------

	То			
From	1	2	3	4
1	0	7D	5D	3D
2	4E	0	0	3D
3	5E	0	0	0
4	6E	0	0	0

(Deliveries indicated by 'D' and Empty moves indicated by 'E') 
**Table 2**: From-To chart showing distances between different stations

	То			
From	1	2	3	4
1	0	150	100	130
2	150	0	NA	80
3	100	NA	0	NA
4	130	NA	NA	0
		(NA: n	ot app	licable)
		<u> </u>		

**Q: 6** (a) Write short notes on:

[18] i) Auxiliary services in plant ii) sewage treatment iii) Effluent water treatment

# **SECTION II**

<b>Q:7</b> (	(a) Explain primary and secondary functions of the maintenance department.	[8]
(	(b) Explain the procedure of preventive periodic maintenance.	[8]
	<u>OR</u>	
Q:8 (	(a) Explain the organization structure of a maintenance department.	[8]
(t	o) Explain various models for calculating life cycle costs.	[8]
<b>Q:9</b> (a	a) Discuss various factors which need to be considered for implementation of el	ficient
	spare part control system.	[8]
(t	o) Explain various types of lubrication systems used in practice.	[8]
	<u>OR</u>	
Q: 10	(a) Explain the techniques for corrosion detection of machinery.	[8]
	(b) Explain atomic absorption spectrometric analysis.	[8]
Q: 11	(a) Explain five steps in fault tree analysis.	[10]
	(b) Explain MTBF, MTTR, and MTTF.	[8]
	OR	
Q: 12	Write short notes on:	[18]
(i	) Reliability centered maintenance	
(i	i) Failure mode and effect analysis.	
(i	ii) Total productive maintenance	

#### 4364\_78 B. E. (Production): 2003 Course: 411085 Sective L : Material Handling and Equipment Desig

-	Elective I : Material Handling and Equipment Design	
Time: 3	Hours Max. M	larks: 100 *****
Instruct	ions to the candidates:	
1) 2) 3) 4) 5) 6) *****	Answer <i>Three</i> questions from Section-I and <i>Three</i> questions from Answers to the two sections should be written in separate books. Neat diagrams must be drawn whenever necessary. Figures to the right indicate full marks. Assume suitable data if necessary. Use of electronic pocket calculator is allowed.	Section-II.
	SECTION-I	
Q.1. (a) I	Explain systems approach to material handling.	(8)
(b)	Explain various factors to be considered during selection of material handlin	ng systems. (8)
	OR	
Q.2.(a)Ez	xplain 'Systematic Handling Analysis' (SHA) of material handling system.	(8)
(b)E	Explain 'Unit load concept' of material handling system.	(8)
Q.3.(a)Ez	xplain principles of material handling system.	(8)
(b) V	Vhat are the objectives of a good material handling system	(8)
	OR	
Q.4.(a)Ez	xplain the following with neat sketch:	
(i	i) Position restricted material handling system	(8)
(i	ii) Line restricted material handling system	(8)
Q.5.(a)Ez	xplain various types of cranes used for material handling with neat sketch	(9)
(b)D	escribe the material handling system used for liquid and gas	(9)
	OR	
Q.6. Writ	te short note on	(18)
(i	i)Roller conveyor and applications	
(i	ii) Material handling systems in casting industry.	
(i	iii)Types of pallets	

# **SECTION-II**

Q.7. (a) Explain advantages and disadvantages of automated material handling system.	(8)	
(b) Explain Robot assisted material handling. State the applications.	(8)	
OR		
Q.8. (a) Describe various hydraulic and pneumatic systems used for Automated Material Handli	ng. (8)	
(b)Explain an automated system of material handling (case study) that is observed by you industry.	u in any (8)	
Q.9.(a)Explain vehicle guidance technology by which AGV pathways are defined.	(8)	
(b)Explain two methods of traffic controls used in commercial AGV.	(8)	
OR		
Q.10.(a)Explain different methods used for assigning AGVs to the task/ job	(8)	
(b) The length of an AS /RS is 400 ft and its height is 100 ft. Horizontal and vertical trave speeds are 250 ft/ min and 80 ft/ min, respectively. The P&D time = $0.6$ min. Determine the		
single and dual command transaction times for the storage system	(8)	
Q.11.(a)Explain Safety aspects considerations in design and operation of material handling equipments.	(9)	
(b)Explain computer applications in material handling.	(9)	
OR		
Q.12.Write short note on	(18)	
(i)RFID system		
(ii)Environmental considerations in material handling		
(iii) Packaging and its effect on selection of material handling.		
***************************************	*****	

# University of Pune [4364]-79 BE Production Engineering 2003 Course Materials and Financial Management

Time : 3 Hours

Max. Marks : 100

# **Instructions** :

- a. Answer any 3 questions from each Section.
- b. Answer 3 questions from Section I and 3 questions from Section II.
- c. Answers to the **two** Sections should be written in **separate** books.
- d. Neat diagrams must be drawn wherever necessary.
- e. Assume suitable data, if necessary.

# SECTION - I

1)			
	i)	What is MPS? Explain relationship of MPS with MRP.	8
	ii)	What are the objectives of inventory control systems	8
		OR	
	iii)	What are the symptoms of poor inventory management?	8
	iv)	Explain need of inventories.	8
2)			
	i)	Explain EOQ concept and its assumptions.	8
	ii)	Explain mathematical extension of basic EOQ model.	8
		OR	
	iii)	With the help of neat diagram explain inventory cost curve.	8
	iv)	What are different types of inventories?	8
3)	Write a	a note on (any 3)	18
	i)	ABC analysis	
	ii)	VED analysis	
	iii)	Stock out cost	

- iv) Procurement cost
- v) Rate of Return with respect to Inventories

# SECTION - II

4)			
	i)	Explain scope of financial management.	8
	ii)	Explain different financial goals.	8
		OR	
	iii)	Explain different financing functions.	8
	iv)	With the help of neat explain role of financial management in government sector.	8
5)			
-,	i)	Compare IRR and NPV.	8
	ii)	What is profitability index? Explain with the help of neat example.	8
		OR	
	iii)	Explain capital rationing	8
	iv)	Explain different investment evaluation criterions.	8
6)	Write a	a note on (any 3)	18
	i)	Cost of capital	
	ii)	Payback period	
	iii)	CAPM	
	iv)	Cost of equity	
	v)	Accounting rate	

[Total No. of Questions: 12]

# UNIVERSITY OF PUNE [4364]-80 B. E. (Production Engineering) Examination - 2013 Process Planning And Tool Selection (2003 Course)(411089)

[Time: 3 Hours]

[Max. Marks: 100]

8

8

# **Instructions:**

- 1 Answer 3 question from section I and 3 questions from section II
- 2 Answers to the two sections should be written in separate answerbooks.
- *3* Black figures to the right indicate full marks.
- 4 Neat diagrams must be drawn wherever necessary.
- 5 Use of calculator and is allowed.
- 6 Assume suitable data, if necessary.

# **SECTION -I**

Q.1	A	Explain the following terms: i) Specification, ii) Part, iii) Assembly, iv) Work-piece v) Operation vi) Equipment vii) Tooling viii) Routing	8
	В	Process engineering is the hub of the organization. Explain.	8
		OR	
Q.2	А	Explain the type of expertise that process engineer should have to discharge his duties in process planning.	8
	В	Draw and explain the diagram relating the operation classifications to the compete manufacturing sequence	8
Q. 3	А	How many functional surface on the part may be identified? Why is originating operations important for process planner to plan the	8

process?
B Explain the following terms:

i) Flaws, ii) Lay, iii) Datum, iv) Surface finish
Also differentiate between rectangular and angular dimensioning system.

OR

Q. 4 A What are the three basic method of measurement of surface roughness explain in detail.

	В	Explain the purpose of grouping related surface or areas?	8
Q. 5	A B	<ul><li>What is the purpose of tolerance chart?</li><li>Define the following terms,</li><li>i) Working dimensions, ii) unequal bilateral tolerance,</li><li>iii) Pasic size</li></ul>	6 6
	С	What is a process tolerance stack? Explain with suitable example. OR	6
Q. 6	A B C	Explain the rules for adding and subtracting the dimensions. Discuss the six possible movements of an object in the space. List the cause of work-piece variations.	6 6 6
		SECTION II	
Q. 7	А	Distinguish between general purpose machine (GPM) and special	8
	В	What is a tool inserts and how it is used? What are the benefits of using inserts over solid tools?	8
Q. 8	А	What are the factors affecting machine selection? Explain.	8
	В	What are the main constraining factors on tool selection? What factors affects on tool performance?	8
Q. 9	A	Explain the following terms: i) Qualifying Operations, ii) Re-qualifying operations iii) Supporting operations	8
	В	What are the advantages and limitations of computer Aided process planning? Name any four CAPP software's. OR	8
Q. 10	А	Explain the difference between product critical areas and process critical areas with a sketch.	8
	В	What are steps in generative process planning system? Explain with a neat flow chart.	8
Q. 11	A	Fig. No1 shows the working drawing of "TENON" with the required dimensions and geometrical tolerance. Stock size is 25 x 15x 30 .The total quantity to be produced is 1000pcs. List the processes that you recommend to produce this part. Propose a process to machine the "TENON".	18



A Prepare a process sheet for a component as shown in Fig. 2. Which is Q. 12 18 to be manufactured in batches of size 600. Analyse the part carefully and prepare the process sheet containing manufacturing plan with operation sequence, equipments, tooling, fixtures, process parameters and sample calculation of operation time.





Title	Material	Qty	Scale	Tolerance
SPINDLE	M.S.	600/Batch	1:1	±0.1

[Total No. of Questions: 12]

[Total No. of Printed Pages: 3]

# **UNIVERSITY OF PUNE**

# [4364]-81

B. E. (Production engg) Examination - 2013

CAD/CAM/CIM (2003 Course)

[Time: 3 Hours]

[Max. Marks: 100]

# **Instructions**

:

- 1 Answer One Question from Section I and Section II
- 2 Answers to the **two sections** should be written in **separate** *answer-books*.
- 3 Neat diagrams must be drawn wherever necessary.
- 4 Assume suitable data, if necessary.

# **SECTION -I**

# Unit I

- Q.1 A Consider A SQUARE ABCD having coordinates A(2,2), 08
   B(5,2), C(5,5), D(2,5).Determine the new position of SQUARE by following transformation-rotate by 30° anti clock wise about A, Scaling by 2 units in X and 1.5 in Y direction.
  - B Explain different operators used in modeling by Boundary 08 representation.

# OR

- Q.2 A Explain the different Network topology in CAD/CAM. 08 B A line XY with end points X(2,2) and Y(5,5), find new co-08
  - ordinates of line for following transformation.
    - 1. Translate X2 unit and Y4 unit
    - 2. Scale in x and y direction by 1.5
    - 3. Rotate by 50degree in CCW,
    - 4. Reflection about origin

Unit II

- Q. 3 A Why tool presetting is required for CNC? Explain the set up 06 with sketch.
  - B What is meant by flexibility in connection with FMS? Explain 06 at least three types of flexibility that can be considered while designing FMS.

C Explain how accurate positioning control is obtained in 06 NC?CNC machines

08

# OR

- Q. 4 A Write a note on
  - i. Automated factory
  - ii. CANQ
  - B Write a CNC program in G and M code for a part as shown in 10 fig No. 1.

Also write a remark for each block.



# Unit III

Q. 5	Α	Explain different input and output reports of MRP-I	08
	В	Explain in brief the following in relation with robot	08
		programming.	
		i. Manual method	
		ii. Walk through method	
		iii. Lead through method	
		OR	
Q. 6	Α	Explain different robot configuration	08

BExplain any two Engineering module in MRP-II08

OR A Explain staircase effect in RP parts. How it will be minimized? 08 Explain with neat sketch fused deposition RP. State its 07 В advantages, limitations. Unit V A Explain concept of group technology. 08 B Explain different co-ordinate system used in FEA. 06

**SECTION II** 

A Why is RP used? Give the details of any one RP process.

Explain with neat sketch steriolithography RP.

C Explain with suitable example the use of coding system in 06 group technology.

08

07

# OR

Q. 10 A A stepped bar is made of two materials joined together as 14 shown in following fig. No. 2. The bar is subjected to an axial pull of 20KN. Determine the displacement, reaction force at support, stress of each of the section using a ID spar element



		A1=75mm <sup>2</sup> , E1=200GPa A2=30mm <sup>2</sup> , E2=120GPa	
	В	What is GSM? State its properties.	06
Unit VI			
Q. 11	Α	Explain with respective to IBM CIM mode	08
		i. Data and work flow integration	
		ii. Enterprise optimization	
	В	Explain the steps in sequential engineering	07
		OR	
Q. 12	Α	Explain ESPRIT Model in brief	08
	В	Explain IBM concept of CIM	07

φ

Unit IV Q. 7

Q. 8

Q. 9

B

[Total No. of Questions: 12]

# **UNIVERSITY OF PUNE** [4364]-82 **B.E.** (Production Engineering) Examination - 2013 **ROBOTICS** (Elective-II) (2003 Course)

[Time: 3 Hours]

[Max. Marks: 100]

# **Instructions:**

Q.4

For a

a)

- 1) Answer Q1 or Q2, Q3 or Q4, Q5 or Q6 from Section I and Q7 or Q8, Q9 or Q10, Q11 or Q12 from Section II
- 2) Answers to the two sections should be written in separate answer-books.
- *3) Figures to the right indicate full marks.*
- 4) Neat diagrams must be drawn wherever necessary.

# **SECTION-I**

- Explain with neat sketch anatomy of a robot. Q.1 a)
  - Find the worst spatial resolution of a spherical robot with 800 mm arm [06] b) length. The robot is equipped with three encoders emitting 1400 pulses per revolution. The linear axis is actuated with the aid of 150 mm pitch lead screw having the encoder mounted on it.

# OR

- Explain with time period the development process in each robot generation. Q.2 a) [10] [06]
  - Define Robot State the laws of Robotics. **b**)
- Q.3 a) For a pick and place type of robot, the link parameters table is given below: [08]

i	$\alpha_{i-1}$	$a_{i-1}$	$d_i$	$\boldsymbol{ heta}_{\mathrm{i}}$
1	0	$90^{0}$	0	$30^{0}$
2	$30^{0}$	0	-2	$0^0$
3	0	5	0	$90^{0}$

Determine the location of the end point of the link 3 with respect to the base.

Explain with neat diagram the joint notations used to designate robot joints. b) [08] OR

			011			
picl	k and place	of robot, the	e link param	eters table i	s given belo	W:
	i	$\alpha_{i-1}$	$a_{i-1}$	$d_i$	$\boldsymbol{ heta}_{\mathrm{i}}$	
	1	$30^{0}$	0	0	$45^{0}$	
	2	$-90^{\circ}$	2	-0	$-45^{\circ}$	
	3	0	0	0	$60^{0}$	

Determine the location of the end point of the link 3 with respect to the base.

Explain the concept of Inverse kinematics. **b**)

[08]

[08]

[10]

- Explain with neat diagram, proximity and range sensor used in robot. Q.5 [08] a) [10]
  - Write a note on Robot vision. **b**)

# OR

- What are the considerations for the design and selection of grippers. Q.6 a)
  - [08] The following data represent a 8X8 array of pixel. Each element in array [10] **b**) indicates the grav level of pixel.

10	17	19	17	19	17	19	12
13	17	19	18	19	19	18	13
14	15	11	19	19	15	10	14
13	10	11	20	20	11	11	13
12	12	12	20	21	12	11	12
11	12	12	19	19	12	10	12
12	18	18	18	19	18	20	11
12	19	19	18	19	20	22	12

Convert t into black and white image.

# **SECTION-II**

<ul> <li>b) How intelligence can be incorporated in robots. [08]</li> <li>OR</li> <li>Q.8 a) Explain 'WAIT', 'DELAY', 'SIGNAL', 'DEPART' commands. [08]</li> <li>b) Describe the structure of any robot programming language with example. [08]</li> <li>Q.9 a) Explain the working of Rs 232 interface. [08]</li> <li>b) Describe the following applications of robot: [08]</li> <li>i) Underwater robot. [08]</li> <li>OR</li> <li>Q.10 a) What is handshaking? Explain hardware handshaking of robot. [08]</li> <li>b) What do you understand from robot economics? [08]</li> <li>Q.11 Write a note on: [18]</li> <li>i) Walking robots (ii) Safety measures in robotics</li> </ul>	a)	Explain the programming methods used in robots.	[08]
OR         Q.8       a)       Explain 'WAIT', 'DELAY', 'SIGNAL', 'DEPART' commands.       [08         b)       Describe the structure of any robot programming language with example.       [08         Q.9       a)       Explain the working of Rs 232 interface.       [08         b)       Describe the following applications of robot:       [08         i)       Underwater robot.       [08         (ii)       Machine loading and unloading       [08         Q.10       a)       What is handshaking? Explain hardware handshaking of robot.       [08         b)       What do you understand from robot economics?       [08         Q.11       Write a note on:       [18         i)       Walking robots       [18         (ii)       Safety measures in robotics       OR	b)	How intelligence can be incorporated in robots.	[08]
<ul> <li>Q.8 a) Explain 'WAIT', 'DELAY', 'SIGNAL', 'DEPART' commands. [08</li> <li>b) Describe the structure of any robot programming language with example. [08</li> <li>Q.9 a) Explain the working of Rs 232 interface. [08</li> <li>b) Describe the following applications of robot: [08</li> <li>i) Underwater robot. [08</li> <li>ii) Machine loading and unloading OR</li> <li>Q.10 a) What is handshaking? Explain hardware handshaking of robot. [08</li> <li>b) What do you understand from robot economics? [08</li> <li>Q.11 Write a note on: [18</li> <li>i) Walking robots (ii) Safety measures in robotics</li> </ul>		OR	
<ul> <li>b) Describe the structure of any robot programming language with example. [08</li> <li>Q.9 a) Explain the working of Rs 232 interface. [08</li> <li>b) Describe the following applications of robot: [08</li> <li>i) Underwater robot. [08</li> <li>ii) Machine loading and unloading OR</li> <li>Q.10 a) What is handshaking? Explain hardware handshaking of robot. [08</li> <li>b) What do you understand from robot economics? [08</li> <li>Q.11 Write a note on: [18</li> <li>i) Walking robots (ii) Safety measures in robotics</li> </ul>	a)	Explain 'WAIT', 'DELAY', 'SIGNAL', 'DEPART' commands.	[08]
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<ul> <li>b) Describe the following applications of robot: [08 i) Underwater robot. (ii) Machine loading and unloading OR</li> <li>Q.10 a) What is handshaking? Explain hardware handshaking of robot. [08 b) What do you understand from robot economics? [08 [08 Q.11 Write a note on: i) Walking robots (ii) Safety measures in robotics</li> </ul>	a)	Explain the working of Rs 232 interface.	[08]
<ul> <li>i) Underwater robot.</li> <li>(ii) Machine loading and unloading</li> <li>OR</li> <li>Q.10 a) What is handshaking? Explain hardware handshaking of robot. [08</li> <li>b) What do you understand from robot economics? [08</li> <li>Q.11 Write a note on:</li> <li>i) Walking robots</li> <li>(ii) Safety measures in robotics</li> </ul>	b)	Describe the following applications of robot:	[08]
(ii) Machine loading and unloading ORQ.10 a) b)What is handshaking? Explain hardware handshaking of robot.[08] [08]Q.11Write a note on: i) Walking robots (ii) Safety measures in robotics[18]		i) Underwater robot.	
ORQ.10a)What is handshaking? Explain hardware handshaking of robot.[08b)What do you understand from robot economics?[08Q.11Write a note on: i) Walking robots (ii) Safety measures in robotics[18		(ii) Machine loading and unloading	
Q.10a)What is handshaking? Explain hardware handshaking of robot.[08b)What do you understand from robot economics?[08Q.11Write a note on: i) Walking robots (ii) Safety measures in robotics[18		OR	
<ul> <li>b) What do you understand from robot economics? [08</li> <li>Q.11 Write a note on: <ul> <li>i) Walking robots</li> <li>(ii) Safety measures in robotics</li> </ul> </li> </ul>	a)	What is handshaking? Explain hardware handshaking of robot.	[08]
Q.11 Write a note on: [18 i) Walking robots (ii) Safety measures in robotics	b)	What do you understand from robot economics?	[08]
<ul><li>i) Walking robots</li><li>(ii) Safety measures in robotics</li></ul>		Write a note on:	[18]
(ii) Safety measures in robotics		i) Walking robots	
<u>OD</u>		(ii) Safety measures in robotics	
UK		OR	
Q.12 Write a note on: [18		Write a note on:	[18]
i) Distance controlled robots		i) Distance controlled robots	
(ii) Robots used in mines		(ii) Robots used in mines	
Q.12		<ul> <li>a)</li> <li>b)</li> <li>a)</li> <li>b)</li> <li>a)</li> <li>b)</li> </ul>	<ul> <li>a) Explain the programming methods used in robots.</li> <li>b) How intelligence can be incorporated in robots.</li> <li>OR</li> <li>a) Explain 'WAIT', 'DELAY', 'SIGNAL', 'DEPART' commands.</li> <li>b) Describe the structure of any robot programming language with example.</li> <li>a) Explain the working of Rs 232 interface.</li> <li>b) Describe the following applications of robot: <ul> <li>i) Underwater robot.</li> <li>(ii) Machine loading and unloading</li> </ul> </li> <li>OR</li> </ul> <li>a) What is handshaking? Explain hardware handshaking of robot.</li> <li>b) What do you understand from robot economics?</li> <li>Write a note on: <ul> <li>i) Walking robots</li> <li>(ii) Safety measures in robotics</li> <li>OR</li> </ul> </li> <li>Write a note on: <ul> <li>i) Distance controlled robots</li> <li>(ii) Robots used in mines</li> </ul></li>

# (4364)-83 **B.E. (Production) Examination May 2013** (2003 Pattern) **Ergonomics And Human Factors Engineering** [Total No. of Printed Pages :2]

Total No. of Questions : 12

[Time: 3 Hours]

# **Instructions:**

- (1) Answers 03 question from section-I & 03 from Section-II
- (2) Figures to the right indicate full marks.
- (3) Neat diagrams must be drawn whenever necessary.
- (4) Assume suitable data, if necessary.

# Section I

<ul><li>Q1. A) What are the objectives of human factors engineering?</li><li>B) Explain design of Manual Materials handling task.</li></ul>	[8] [10]
OR	
Q2. A) Explain the basis for ergonomic problem identification.	[9]
B) What is biomechanics? Elaborate with a practical example.	[9]
<ul><li>Q3. A) What is anthropometry? Explain the principles in the application of its data B) Explain any two principles of arrangements of components in various working conditions.</li></ul>	[10] [6]
OR	
<ul><li>Q4. A) Explain the consideration in the design of a seated workplace.</li><li>B) What are the requirements for designing a safe product?</li></ul>	[10] [6]

[Max. Marks: 100]

# 1

OR

Q5. Explain the arrangement of any four of the following components at	
workplace	[16]

- 1. Visual Displays
- 2. Control Panels
- 3. Hand Controls
- 4. Multifunction Hand controls
- 5. Mirror hand arrangements
- 6. Data applies in arrangement of components in physical space

#### OR

Q6. A) Discuss the concept of visibility. How is it related with elderly people? [8]B) What do you mean by vibration Syndrome? How is it critical in hand tool design? [8]

# SECTION II

Q7. A) Explain any three temperature indices and its relativity with each other.	[12]
B) Write a note on glare and its importance in illumination.	[6]

#### OR

Q8. A) Explain any two effects heat on human performance	[8]
B) Discuss the techniques of noise reduction.	[10]

Q9. A) Explain the work and rest cycle in accordance with Human Factors Engineering

	L - 1
B) Discuss the role of learning curves for application in ergonomics.	[8]

#### OR

Q10. Explain any three important phases in application of ergonomics in systems

#### Design

Q11. What is work factor System? How is it important to study its component for Human Factors Engineer? Discuss its types in brief [16]

#### OR

Q12. A) Explain the reach element in MTM 1. What are its classes?	[8	3]	
---	----	----	--

B) How is PMTS got evolved from traditional concepts of work study? Discuss its importance from a perspective of industrial engineer. [8]

[16]

[8]

[Total No. of Questions: 12]

# UNIVERSITY OF PUNE [4364]-85 B. E. (PRODUCTION ENGINEERING) Examination 2013 ADVANCED PRODUCTION TECHNOLOGY ELETIVE-II (411090) (2003 Course)

[Time: 3 Hours]

# [Max. Marks: 100]

Instructions:

- (1) Answer any three questions from Section I and any three questions from Section II
- (2) Answers to the two Sections should be written in separate answer-books
- (3) Neat diagram must be drawn wherever necessary.

# **SECTION I**

# UNIT-I

Q.1 A) Explain the basic frame work of TPS	[8]
b) Explain the various KANBAN Rules with their subrules	[8]
OR	
Q.2 A) Explain the concept of automation in TPS	[8]
B) Illustrate a JIT system with the help of neat block diagram	[8]
UNIT –II	
Q.3 A) What is value stream mapping and explain its importance in industry.	[8]
B) What is reverse engineering? Compare it with Business process	[9]
reengineering.	
OR	
Q.4 A) Explain with neat sketch various activities involved in SMED	[9]
B) What is performance of manufacturing? state which data has to be	[8]
collected and report to be prepared for measuring performance of	
manufacturing.	
UNIT-III	
Q.5 A) Describe the various hard and soft factors of the organisation for	[8]
productivity improvement	
B) What is productivity? Explain different types of productivity and its measurement in manufacturing industry.	[9]

OR	
Q.6 A) Describe the various factors for productivity improvement in small scale industries	[9]
B) What is MBO? Explain steps in MBO.	[8]
SECTION-II	
UNIT-IV	
Q.7 A) Explain the concept of simulation in manufacturing industry?	[9]
B) Explain how data collection will be done in expert system OR	[8]
Q.8 A) What is Artificial Intelligence? Explain its applicability in manufacturing	[8]
B) Explain to create a logical rule for decision making in AI?	[9]
(0.9  A) explain methodology for system design in manufacturing?	[8]
P) What moont by the design synthesis and functional analysis in design	[0] [0]
b) what meant by the design synthesis and functional analysis in design	႞၀၂
	503
Q.10 A) Explain with suitable example the importance of tolerance analysis in product design.	[8]
B) What is feasibility analysis? Explain why it is carried out	[8]
UNIT VI	
Q.11 A) What is innovation? Explain its importance for surviving the industry with suitable example	[9]
B) Explain the role of government in technology development	[8]
OR	[0]
O(12  A) Explain the impact of technology on society and business	[0]
a D) Explain in datail the avalution of technology management	[ / ا ر ما
s by Explain in detail the evolution of technology management	၂၀၂